

Spiral plat sans courbes terminales

Déformée élastique en position horizontale

Cas d'une montre bracelet

Caractéristiques du spiral

➔ Référence : E:\Résonateur (TA)\Data\Bal_spiral plat (ex num).mcd(R)

➔ Référence : E:\Résonateur (TA)\Data\Définition Atan.mcd(R)

Dimensions $\acute{e}p = 0.03 \text{ mm}$ $ha = 0.15 \text{ mm}$ $S = 4.5 \times 10^{-3} \text{ mm}^2$ $TOL := 10^{-9}$

$d2_{sp} = 4.52 \text{ mm}$ $d1_{sp} = 1.1 \text{ mm}$ $p_{sp} = 0.135 \text{ mm}$ $n_{sp} = 12.667$

$L := L_{sp}$ $L = 11.182 \text{ cm}$ $\psi_0 := 2 \cdot \pi \cdot n_{sp}$ $\psi_0 = 4.56 \times 10^3 \text{ deg}$

Position du piton $r_P := 0.5 \cdot d2_{sp}$ $\alpha_P := 0$ $x_P := r_P \cdot \cos(\alpha_P)$ $y_P := r_P \cdot \sin(\alpha_P)$
 $x_P = 2.26 \text{ mm}$ $y_P = 0 \text{ mm}$ $z_P := x_P + i \cdot y_P$

Position du point d'attache à la virole $r_V := 0.5 \cdot d1_{sp}$ $\alpha_V(\theta) := \psi_0 + \theta$ $x_V(\theta) := r_V \cdot \cos(\alpha_V(\theta))$ $y_V(\theta) := r_V \cdot \sin(\alpha_V(\theta))$

Forme naturelle du spiral

$a := \frac{p_{sp}}{2 \cdot \pi}$ $r_s(\alpha) := r_P - a \cdot \alpha$ $x_{0s}(\alpha) := r_s(\alpha) \cdot \cos(\alpha)$ $y_{0s}(\alpha) := r_s(\alpha) \cdot \sin(\alpha)$ $z_0(\alpha) := r_s(\alpha) \cdot \exp(i \cdot \alpha)$

$r'(\alpha) := \frac{d}{d\alpha} r_s(\alpha)$ $s(\alpha) := \frac{\pi}{p_{sp}} \cdot (r_P^2 - r_s(\alpha)^2)$ $s(\alpha) := r_P \cdot \alpha - \frac{a}{2} \cdot \alpha^2$ $s(\psi_0) = 11.182 \text{ cm}$

Amplitude stationnaire du balancier $\theta_0 = 270 \text{ deg}$

Contrainte maximum

➔ Référence : E:\Résonateur (TA)\Tables\Modules J, I et W des barres élastiques.mcd(R)

$I_{33} := I_{f_rect}(\acute{e}p, ha)$ $W_{f3} := W_{f_rect}(\acute{e}p, ha)$ $\sigma_{max} := \frac{E \cdot I_{33}}{L \cdot W_{f3}} \cdot \theta_0$ $\sigma_{max} = 132.293 \frac{N}{\text{mm}^2}$

Déformée du spiral avec la virole non liée à l'axe de balancier

$$z_1(\theta, \alpha) := z_P + \int_0^\alpha \exp(i \cdot \varphi_0(\alpha')) \cdot \exp\left(i \cdot \theta \cdot \frac{s(\alpha')}{L}\right) \cdot r_s(\alpha) d\alpha'$$

$$z'_0(\alpha) := \left[-a + i \cdot (r_P - a \cdot \alpha)\right] \cdot \exp(i \cdot \alpha)$$

$$z_1(\theta, \alpha) := z_P + \int_0^\alpha z'_0(\alpha') \cdot \exp\left(i \cdot \theta \cdot \frac{s(\alpha')}{L}\right) d\alpha'$$

$$z_1(\theta, \alpha) := z_P + \int_0^\alpha \left[-a + i \cdot (r_P - a \cdot \alpha')\right] \cdot \exp\left[i \cdot \alpha' \cdot \left[1 + \frac{\theta}{L} \cdot \left(r_P - \frac{a}{2} \cdot \alpha'\right)\right]\right] d\alpha'$$

Graphe de la déformation

Forme naturelle

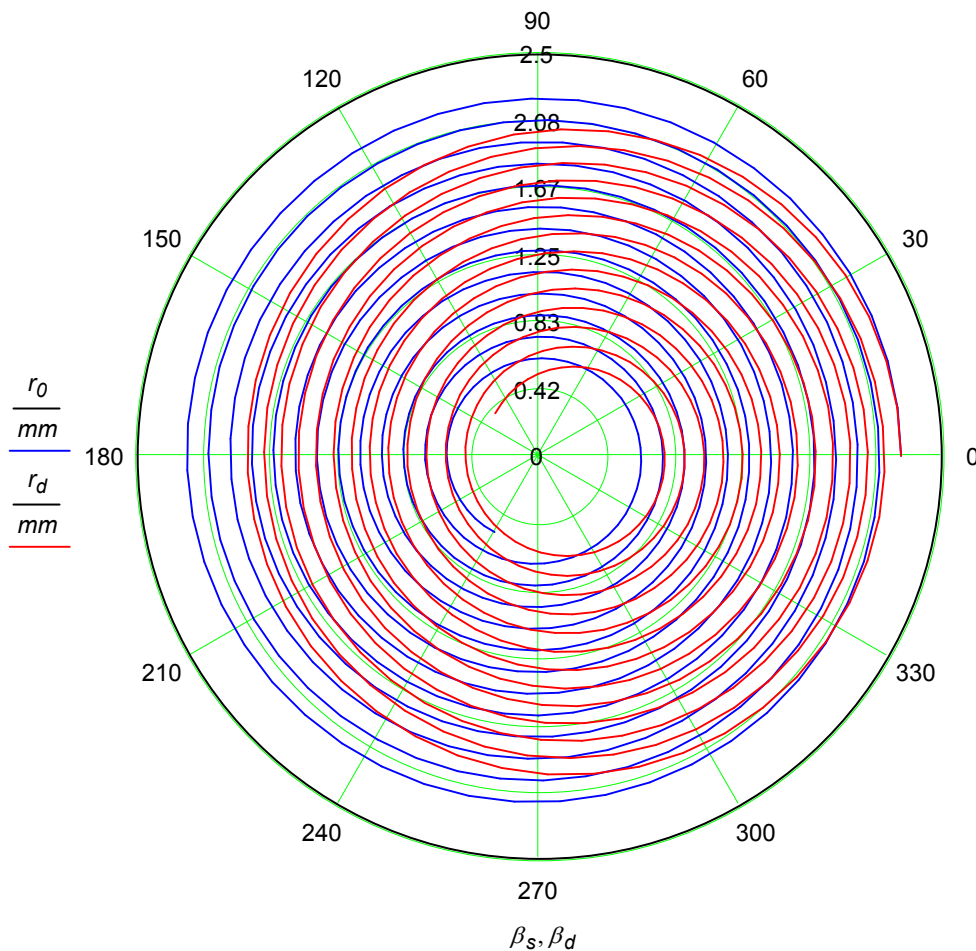
$$n := 50 \cdot \text{partenti\`ere}(n_{sp}) + 1 \quad i := 0..n-1 \quad \Delta\alpha := \frac{\psi_0}{n-1} \quad \alpha_i := i \cdot \Delta\alpha$$

$$x_{0_i} := x_{0s}(\alpha_i) \quad y_{0_i} := y_{0s}(\alpha_i) \quad r_0 := \sqrt{x_0^2 + y_0^2} \quad \beta_s := \overrightarrow{\text{Atan}(x_0, y_0)}$$

Déformée

$$z_{d_i} := z_1(\theta_0, \alpha_i) \quad n_{pt} := \text{dernier}(z_d) \quad x_d := \text{Re}(z_d) \quad y_d := \text{Im}(z_d) \quad r_d := |z_d| \quad r_{d_{n_{pt}}} = 0.378 \text{ mm}$$

$$\beta_d := \overrightarrow{\text{Atan}(x_d, y_d)} \quad \beta_{d_0} = 0 \text{ deg} \quad \beta_{d_{n_{pt}}} = 135.516 \text{ deg} \quad \text{mod}(\alpha_v(\theta_0), 2 \cdot \pi) = 150 \text{ deg}$$



$$x_v(\theta_0) = -0.476 \text{ mm} \quad x_{d_{n_{pt}}} - x_v(\theta_0) = 0.207 \text{ mm} \quad y_v(\theta_0) = 0.275 \text{ mm} \quad y_{d_{n_{pt}}} - y_v(\theta_0) = -0.01 \text{ mm}$$

Déplacement de la virole libre

$$\Delta \mathbf{1}(\theta) := \frac{i \cdot \theta}{L} \cdot \int_0^{\psi_0} \exp \left[i \cdot \alpha \cdot \left[1 + \frac{\theta}{L} \cdot \left(r_P - \frac{a}{2} \cdot \alpha \right) \right] \right] \cdot (r_P - a \cdot \alpha)^2 d\alpha$$

$$u_1(\theta) := \text{Re}(\Delta \mathbf{1}(\theta)) \quad v_1(\theta) := \text{Im}(\Delta \mathbf{1}(\theta)) \quad u_1(\theta_0) = -0.207 \text{ mm} \quad v_1(\theta_0) = 0.01 \text{ mm}$$

Calcul des réactions sur la virole

$$\begin{aligned}\xi_{0s} &:= \frac{1}{L} \cdot \int_0^{\psi_0} x_{0s}(\alpha) \cdot r_s(\alpha) d\alpha & \eta_{0s} &:= \frac{1}{L} \cdot \int_0^{\psi_0} y_{0s}(\alpha) \cdot r_s(\alpha) d\alpha \\ q_{20s} &:= \frac{1}{L} \cdot \int_0^{\psi_0} y_{0s}(\alpha)^2 \cdot r_s(\alpha) d\alpha & p_{20s} &:= \frac{1}{L} \cdot \int_0^{\psi_0} x_{0s}(\alpha)^2 \cdot r_s(\alpha) d\alpha & k_{0s} &:= \frac{1}{L} \cdot \int_0^{\psi_0} x_{0s}(\alpha) \cdot y_{0s}(\alpha) \cdot r_s(\alpha) d\alpha \\ \xi_{0s} &= -1.361 \times 10^{-3} \text{ mm} & \eta_{0s} &= 0.047 \text{ mm} & q_{20s} &= 1.352 \text{ mm}^2 & p_{20s} &= 1.353 \text{ mm}^2 & k_{0s} &= 0.026 \text{ mm}^2 \\ \mathbf{S}_0 &:= \frac{L}{E \cdot I_{33}} \cdot \begin{pmatrix} q_{20s} - \eta_{0s}^2 & \eta_{0s} \cdot \xi_{0s} - k_{0s} \\ \eta_{0s} \cdot \xi_{0s} - k_{0s} & p_{20s} - \xi_{0s}^2 \end{pmatrix} & \mathbf{R}'(\theta) &:= \mathbf{S}_0^{-1} \cdot \begin{pmatrix} u_1(\theta) \\ v_1(\theta) \end{pmatrix} & \mathbf{R}'(\theta_0) &= \begin{pmatrix} -9.673 \times 10^{-5} \\ 2.943 \times 10^{-6} \end{pmatrix} \text{ N} \\ & & & & |\mathbf{R}'(\theta_0)| &= 9.678 \times 10^{-5} \text{ N}\end{aligned}$$

Approximations de Haag

$$\begin{aligned}\mathbf{OP} &:= r_P & \mathbf{OV} &:= r_V \cdot e^{i \cdot \psi_0} & \Delta \mathbf{1}(\theta_0) &= -0.207 + 0.01i \text{ mm} \\ \mathbf{w}(\theta) &:= \frac{-\theta}{L} \cdot \left[\left(r_P - 2 \cdot i \cdot a - \frac{\theta}{L} \cdot r_P^2 \right) \cdot \mathbf{OP} - \left(r_V - 2 \cdot i \cdot a - \frac{\theta}{L} \cdot r_V^2 \right) \cdot \mathbf{OV} \cdot e^{i \cdot \theta} \right] & \mathbf{w}(\theta_0) &= -0.205 + 0.011i \text{ mm} \\ q_{20s} &= 1.352 \text{ mm}^2 & q_{20s} - \eta_{0s}^2 &= 1.35 \text{ mm}^2 & p_{20s} &= 1.353 \text{ mm}^2 & p_{20s} - \xi_{0s}^2 &= 1.353 \text{ mm}^2 \\ \sigma_2 &:= \frac{1}{L} \cdot \int_0^{\psi_0} z_0(\alpha) \cdot \overline{z_0(\alpha)} \cdot r_s(\alpha) d\alpha & \sigma_2 &:= \frac{1}{2} \cdot (r_P^2 + r_V^2) & \sigma_2 &= 2.705 \text{ mm}^2 \\ \mathbf{R}'(\theta) &:= \frac{E \cdot I_{33}}{L} \cdot \frac{2}{\sigma_2} \cdot \begin{pmatrix} u_1(\theta) \\ v_1(\theta) \end{pmatrix} & \mathbf{R}'(\theta_0) &= \begin{pmatrix} -9.658 \times 10^{-5} \\ 4.806 \times 10^{-6} \end{pmatrix} \text{ N} & |\mathbf{R}'(\theta_0)| &= 9.67 \times 10^{-5} \text{ N} \\ \mathbf{F}(\theta) &:= \frac{-2 \cdot E \cdot I_{33}}{L^2 \cdot \sigma_2} \cdot \theta \cdot r_P \cdot \left[\left(1 - \frac{\theta}{L} \cdot r_P \right) \cdot \mathbf{OP} \right] & \mathbf{F}(\theta_0) &= -9.095 \times 10^{-5} \text{ N}\end{aligned}$$

Deuxième approximation de la déformée du spiral

$$\begin{aligned}x_1(\theta, \alpha) &:= \text{Re}(z_1(\theta, \alpha)) & y_1(\theta, \alpha) &:= \text{Im}(z_1(\theta, \alpha)) & \mathbf{R}'_x(\theta) &:= \mathbf{R}'(\theta)_0 & \mathbf{R}'_y(\theta) &:= \mathbf{R}'(\theta)_1 \\ s\xi_1(\theta, \alpha) &:= \int_0^\alpha x_1(\theta, \alpha') \cdot r_s(\alpha') d\alpha' & \xi_{1s}(\theta) &:= \frac{1}{L} \cdot s\xi_1(\theta, \psi_0) & \xi_{1s}(\theta_0) &= 0.199 \text{ mm} \\ s\eta_1(\theta, \alpha) &:= \int_0^\alpha y_1(\theta, \alpha') \cdot r_s(\alpha') d\alpha' & \eta_{1s}(\theta) &:= \frac{1}{L} \cdot s\eta_1(\theta, \psi_0) & \eta_{1s}(\theta_0) &= 0.037 \text{ mm} \\ sp_{21}(\theta, \alpha) &:= \int_0^\alpha x_1(\theta, \alpha')^2 \cdot r_s(\alpha') d\alpha' & p_{21}(\theta) &:= \frac{1}{L} \cdot sp_{21}(\theta, \psi_0) & p_{21}(\theta_0) &= 1.207 \text{ mm}^2 \\ sq_{21}(\theta, \alpha) &:= \int_0^\alpha y_1(\theta, \alpha')^2 \cdot r_s(\alpha') d\alpha' & q_{21}(\theta) &:= \frac{1}{L} \cdot sq_{21}(\theta, \psi_0) & q_{21}(\theta_0) &= 1.168 \text{ mm}^2 \\ sk_1(\theta, \alpha) &:= \int_0^\alpha x_1(\theta, \alpha') \cdot y_1(\theta, \alpha') \cdot r_s(\alpha') d\alpha' & k_1(\theta) &:= \frac{1}{L} \cdot sk_1(\theta, \psi_0) & k_1(\theta_0) &= 0.027 \text{ mm}^2\end{aligned}$$

